slide for ICIAM2015 (PP-A01-6) Novel Krylov-subspace Solver of Generalized Shifted Linear Equations for Massively Parallel Quantum Material Simulations

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Note: The present slide appears as http://www.damp.tottori-u.ac.jp/~hoshi/info/slide_hoshi_201508_ICIAM_lt.pdf

abstract

Novel Krylov-subspace algorithms were developed for massively parallel quantum material simulations or electronic structure calculations. The method solves the generalized shifted linear equations ((zS-H) x = b), instead of conventional generalized eigen-value equation. The paper presents the algorithms and the results of 100-nm-scale or one-hundred-million-atom materials on the K supercomputer with a high parallel efficiency.

The paper also presents recent linear-algebraic algorithms based on time-dependent Schrodinger-type equations and its application to organic electronics materials

Note: a recent review: T. Hoshi, et al., PoS 020, 65 (2014) http://pos.sissa.it/archive/conferences/202/065/IWCSE2013_065.pdf 1. ELSES, our quantum material simulation code

(ELSES = Extra-Large-Scale Electronic Structure calculation code) Benchmark with upto 100M atoms(\rightleftharpoons Si : (126nm)³region)

aPF :amourphous-like conjugated polymer, poly-(9,9 dioctil-fluorene), NCCS: sp2-sp3 nano composite carbon solid



Ref. T. Hoshi, K. Yamazaki, Y. Akiyama, JPS-CP 1, 016004 (2014).

2. Nano-material studies with ELSES (http://www.elses.jp/)

Acknowledge (co-worker, data supply) : S. Nishino, T. Fujiwara (U. Tokyo), S. Yamamoto (Tokyo Eng U) H. Yamasaki (Toyota), Y. Zempo (Hosei U), M. Ishida (Sumitomo Chem.)



(d) Amourphous-like conjugated polymer: poly (9,9) dioctyl-fluorene (opto-electronics material)



(e) Ionic liquid : PP13–TFSI (battery problem)



(f) Li⁺-ion diffusion in solid (battery problem)



Note: calculations with modelled (TB-type) quantum theories based on ab initio calculation

3. Application-Algotirhm-Architecture co-design

→ Construct an optimal workflow for each target physical quantity





5. Novel linear algebraic algorithms

Solvers with

 \rightarrow Krylov subspace solvers for generalized shifted linear equation

$$(H - zS)x = b$$

Galerkin Principle Residual Theorem(*) gLanczos, gArnoldi, mArnodi, Arnoldi(M,W,G)

> (*) A. Frommer, Computing 70, 87 (2003)

Solvers with Collinear

gsCOCG,

gsQMR

Our recent papers

[1] H. Teng, et al., Phys. Rev. B 83, 165103 (2011). [2] T. Hoshi, et al, J. Phys. Cond. Matt. 24, 165502 (2012). [3] T. Sogabe, et al., J. Comp. Phys. 231, 5669 (2012). [4] S. Iwase et al., Phys. Rev. E 91, 063305 (2015).

The other papers can be found in our webpage: http://www.damp.tottori-u.ac.jp/~hoshi/ 6. Example : multiple Arnoldi (mArnoldi) method

Original problem : $Hy = \lambda Sy$ (generalized eigen-value equation) (1)

H,S: real-symmetric, S: positive definite

Use of 'multiple Krylov subspaces', for obtaining the approximate eigen vectors,

$$\mathcal{L} \equiv K_p(H; \boldsymbol{b}) \oplus K_q(H; S^{-1}\boldsymbol{b}) \quad (2)$$

= span{ $\boldsymbol{u}_1, \boldsymbol{u}_2, \dots, \boldsymbol{u}_{\nu}$ } ($\boldsymbol{u}_i^T S \boldsymbol{u}_j = \delta_{i,j}$) ($\nu \equiv p + q$)

Tutorial: Krylov subspace

$$K_n(A; \boldsymbol{b}) \equiv \operatorname{span}\left\{\boldsymbol{b}, A\boldsymbol{b}, A^2\boldsymbol{b}, ..., A^{n-1}\boldsymbol{b}\right\}$$

n : subspace dimension (iteration number)



Details of rhe multiple Arnoldi method (1)

Original problem : $H \boldsymbol{y} = \lambda S \boldsymbol{y}$ (1) Def: Subspace

$$\mathcal{L} \equiv K_p(H; \boldsymbol{b}) \oplus K_q(H; S^{-1}\boldsymbol{b})$$

= span{ $\boldsymbol{u}_1, \boldsymbol{u}_2, ..., \boldsymbol{u}_{\nu}$ } (2)
 $(\nu \equiv p+q)$

with the 'S'-orthogonality of $\{u_m\}$

$$\boldsymbol{u}_i^T S \boldsymbol{u}_j = \delta_{i,j} \tag{3}$$

Def: Subspace (approximate)

eigen pairs of
$$(\varepsilon_{\alpha}, \boldsymbol{v}_{\alpha}) \ (\boldsymbol{v}_{\alpha} \in \mathcal{L})$$

 $\boldsymbol{v}_{\alpha} = \sum_{n}^{\nu} C_{n\alpha} \boldsymbol{u}_{n}$ (4)

Def: The residual vector

$$\boldsymbol{r}_{\alpha} \equiv (H - \varepsilon_{\alpha} S) \boldsymbol{v}_{\alpha}$$
 (5)

 r_{α}

The Galerkin principle ($r_{lpha} \perp \mathcal{L}$)

determines the subspace eigen pairs

by the standard eigen-value problem of $\sum_{\nu}^{\nu} \mathcal{H} = C$

$$\sum_{n} \mathcal{H}_{mn} C_{n\alpha} = \varepsilon_{\alpha} C_{m\alpha} \tag{6}$$

with the 'reducced' ($v \ge v$) matrix $\mathcal{H}_{mn} \equiv \boldsymbol{u}_n^{\mathrm{T}} H \boldsymbol{u}_m$ (7)

The subspace Green function is given by

$$G^{(b)} \equiv \sum_{\alpha}^{\nu} \frac{\boldsymbol{v}_{\alpha} \boldsymbol{v}_{\alpha}^{\mathrm{T}}}{z - \varepsilon_{\alpha}}$$
(8)

Details of rhe multiple Arnoldi method (2)



Details of rhe multiple Arnoldi method (3): Proof of 'projection theorem'

Def.: subspace

$$\mathcal{L} \equiv K_p(H; \boldsymbol{b}) \oplus K_q(H; S^{-1}\boldsymbol{b})$$

= span{ $\boldsymbol{u}_1, \boldsymbol{u}_2, ..., \boldsymbol{u}_{\nu}$ }
($\boldsymbol{u}_i^T S \boldsymbol{u}_j = \delta_{i,j}$)

Def.: Density matrix in the FFL

 $\Omega \equiv \sum_{\alpha}^{\nu} \boldsymbol{u}_{\alpha} \boldsymbol{u}_{\alpha}^{\mathrm{T}}$ Theorem for physical quantity: If $q \neq 0$, the $\boldsymbol{b}^{\mathrm{T}} \Omega X \boldsymbol{b} = (\mathrm{exact})$ Proof

'projection theorem': $\Omega S oldsymbol{\gamma} = oldsymbol{\gamma}$ (a) for any verctor in the subspace $(\gamma \in \mathcal{L})$ Note: $\Omega = S^{-1}$ (b) in the exact solution. If $q \neq 0$, then $S^{-1} \boldsymbol{b} \in \mathcal{L}$ and the 'projection' theorem of (a) gives $\Omega S(S^{-1}\boldsymbol{b}) = (S^{-1}\boldsymbol{b})$ (C) or $\Omega \boldsymbol{b} = S^{-1} \boldsymbol{b}$ (d) Therefore $\boldsymbol{b}^{\mathrm{T}} \Omega X \boldsymbol{b} = \boldsymbol{b}^{\mathrm{T}} S^{-1} X \boldsymbol{b}$ (exact) (e)

7. Another problem : Recent study for organic electronics device

(a) Original PDE: quantum 'wave' dynamics with a Schrödinger-type equation

$$\partial_t u = -iHu$$
 (1)

(b) Discretization with given functions $\{f_i(m{r})\}$ (localized near atoms)

$$u(\boldsymbol{r},t) \Rightarrow \boldsymbol{u}(t) \equiv (u_1,u_2,...,u_N)^{\mathrm{T}}$$
 (2)

ightarrow its formal solution (ightarrow linear algebraic problems)

$$\boldsymbol{u}(t+\delta t) := e^{-i\delta tH}\boldsymbol{u}(t)$$

Fig(below) : The real part is drawn by the two isosurfaces (${
m Re}[u(m{r},t)]=\pm C$)



(*) Experiment and theory : J. Terao, et al., Nature Comm. 4, 1691 (2013)

(3)

$$u(oldsymbol{r},t)\equiv\sum_{i}u_{i}f_{i}(oldsymbol{r})$$
 (4)

Appendix: 'ELSES matrix library' (http://www.elses.jp/matrix/)

- A sparse matrix collection arising in our real problems
 - \Rightarrow Prepared for future numerical analysis researches
 - \Rightarrow The matrix sizes : $M = 10^2 \sim 10^6$ / The data format: the Matrix Market format



Notice: a related talk in this conference

CP-Th-D-14-5:

'Parallel generalized eigenvalue computation with hybrid solvers and their benchmark on supercomputers'

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